

# Robust Bayes Inference for Non-identified SVARs

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Capri, 26/6/14

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  - Often forced to restrict attention to small SVARs  $\rightarrow$  tradeoff between model fit and plausibility of restrictions
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- Econometric challenges:
  - Frequentist inference in partially identified models unappealing because: 1) relies on asymptotic approximation; 2) computationally cumbersome; 3) validity not proven for general equality and inequality restrictions
  - Bayesian inference attractive but sensitive to prior choice: effect does not disappear asymptotically under partial identification (Poirier, 1998; Baumeister and Hamilton, 2013)

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  - Give easy to verify conditions that guarantee convexity
- Use robust Bayesian method that overcomes sensitivity to prior choice
  - Show that our estimated set converges asymptotically to true identified set, unlike current Bayesian methods

# Partially identified SVARs

- n-variable SVAR with orthogonal shocks:

$$A_0 y_t = a + \sum_{j=1}^p A_j y_{t-j} + \epsilon_t, \quad \epsilon_t \sim \mathcal{N}(0, I_n),$$

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$$y_t = b + \sum_{j=1}^p B_j y_{t-j} + u_t, \quad u_t \sim \mathcal{N}(0, \Sigma)$$

where  $\Sigma = A_0^{-1} (A_0^{-1})'$



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- Reduced-form parameters are  $\phi = (B, \Sigma)$

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- Impulse-response function at horizon  $h$  is  $IR^h = C_h(B) A_0^{-1}$

# Partially identified SVARs

- Following analysis in Uhlig (2005), without identifying restrictions, knowledge of  $\phi$  corresponds to a set of observationally equivalent  $A_0$ 's

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- $Q$  is any orthonormal "rotation" matrix
- $\Sigma_{tr}$  is the Cholesky factor  $\Sigma = \Sigma_{tr}\Sigma_{tr}'$
- This corresponds to a set of observationally equivalent impulse-responses

$$IR^h \equiv C_h(B)\Sigma_{tr}Q$$

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  - 3 Draw  $\phi$ 's from the posterior and  $Q$ 's from the **uniform prior**
  - 4 Retain the draws of  $IR^h = C_h(B)\Sigma_{tr}Q$  that satisfy the sign restrictions (+ sign normalizations)

# Pitfalls of Bayesian inference in partially identified models

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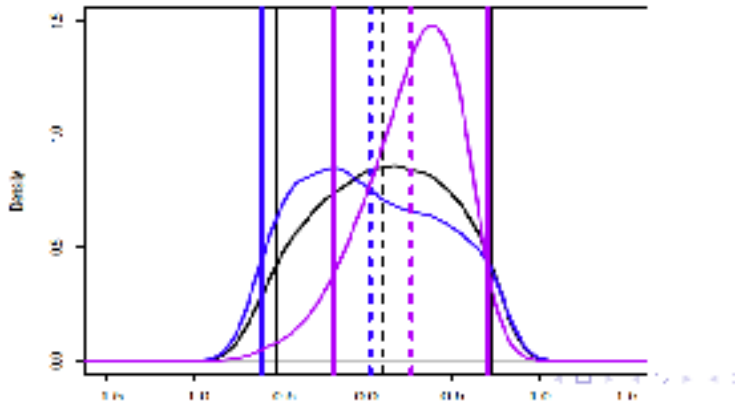
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- Challenge:
  - Difficult to specify plausible informative prior for  $Q$
  - Uninformative (uniform) prior for  $Q$  can give informative prior for  $IR^h \rightarrow$  can affect posterior inference for impulse-responses

# Illustration of prior sensitivity

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- SVAR from Aruoba & Schorfheide (2011) with sign restrictions.
- 3 different priors for  $Q$  (uniform for each shock but different correlation among shocks)



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- We take different approach: from agnostic belief to "ambiguous" belief  $\rightarrow$  multiple prior for non-identified aspects of the model (here  $Q$ )
- Robust Bayes approach to inference (Berger & Berliner, 1986, Wasserman, 1990)

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- → this makes the inference robust to the prior for drawing  $Q$ 's
- → our estimated set ("posterior bounds") converges asymptotically to true identified set

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$$F(\phi, Q) \equiv \begin{pmatrix} F_1(\phi)q_1 \\ \vdots \\ F_j(\phi)q_j \\ \vdots \end{pmatrix} = 0, \quad F_j(\phi): f_j \times n.$$

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- Without loss of generality, order the variables in such way that  $f_1 \geq f_2 \geq \dots \geq f_n \geq 0$ .

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- $IR^h[i, j] = 0$ . Since  $IR^h = C_h(B)\Sigma_{tr}Q$ , restriction is  $c_{ih}(\phi)' q_j = 0$
- $IR^\infty[i, j] = 0$ . Since  $IR^\infty = (I - \sum_{l=1}^p B_l)^{-1}\Sigma_{tr}Q$ , restriction is  $c_{i\infty}(\phi)' q_j = 0$

# Sign restrictions

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- Stack the sign restrictions over multiple shocks, and represent them by  $S(\phi, Q) \geq 0$ .

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- The set of feasible  $Q$ 's:

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- The identified set for  $r$  :

$$IS_r = \{r(\phi, Q) : Q \in \mathcal{Q}(\phi|F, S)\}$$

# Results on convexity of identified set

- 1 Equality restrictions only:  $IS_r$  is a convex set  $IS_r = [l(\phi), u(\phi)]$  if  $f_i \leq n - i$  for all  $i = 1, \dots, n$

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- 3 Sign restrictions on multiple shocks can yield non-convex identified sets

# Constructing the agnostic prior class

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- Choose single prior for  $\phi$  but multiple prior for  $Q|\phi$
- The posterior of the impulse response  $r$  given the data  $Y$  can be written as

$$\pi_{r|Y}(A) = \int_{\phi} \pi_{r|\phi}(A) d\pi_{\phi|Y}$$

where  $\pi_{r|\phi}(A) = \pi_{Q|\phi}(r(\phi, Q) \in A)$



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- Consider the class of all conditional priors  $\pi_{Q|\phi}$  that assign probability one to the set  $\mathcal{Q}(\phi|F, S)$  :

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- Then the agnostic class of joint priors is

$$\Pi_{\phi Q} = \left\{ \pi_{Q|\phi} \pi_\phi : \pi_{Q|\phi} \in \Pi_{Q|\phi} \right\}$$

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$$\Pi_{\phi Q|Y} = \{\pi_{Q|\phi} \pi_{\phi|Y} : \pi_{Q|\phi} \in \Pi_{Q|\phi}\}$$

# Posterior bounds in theory

- For a convex identified set  $IS_r = [l(\phi), u(\phi)]$ , we propose reporting the posterior mean bounds

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- Restricting attention to convex sets makes computation of posterior mean bounds simple, once we show how to draw  $Q$ 's that are compatible with equality and inequality restrictions

# Posterior bounds in practice

- Specify  $\pi_\phi$  and get  $\pi_{\phi|\gamma}$  from the reduced form VAR



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- Draw  $\phi \sim \pi_{\phi|Y}$ , and check if  $\mathcal{Q}(\phi|F, S)$  is nonempty
- If  $\mathcal{Q}(\phi|F, S)$  is nonempty, solve

$$\begin{aligned} & \max / \min_Q r(\phi, Q) \\ \text{s.t. } & Q'Q = I_n, \quad F(\phi, Q) = 0, \quad S(\phi, Q) \geq 0 \end{aligned}$$

to obtain  $l(\phi)$  and  $u(\phi)$

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- Repeat Step 2 and 3 to obtain many draws of  $(l(\phi), u(\phi))$

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- Draw  $\phi \sim \pi_{\phi|Y}$ , and check if  $Q(\phi|F, S)$  is nonempty
- If  $Q(\phi|F, S)$  is nonempty, solve

$$\begin{aligned} & \max / \min_Q r(\phi, Q) \\ \text{s.t. } & Q'Q = I_n, \quad F(\phi, Q) = 0, \quad S(\phi, Q) \geq 0 \end{aligned}$$

to obtain  $l(\phi)$  and  $u(\phi)$

- Repeat Step 2 and 3 to obtain many draws of  $(l(\phi), u(\phi))$
- Report means of draws  $\left[ \widehat{E}_{\phi|Y} l(\phi), \widehat{E}_{\phi|Y} u(\phi) \right]$

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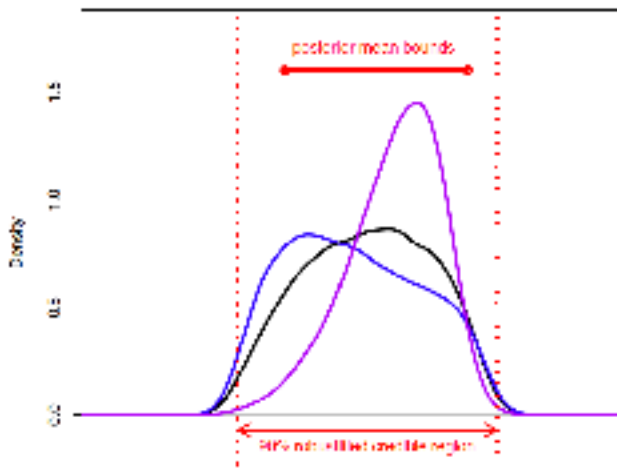
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- In words: "the shortest interval to which all the posteriors assign probability at least  $\alpha$ "

# The output of our procedure

- Consider again Aruoba Schorfheide (2011) example of SVAR with sign restrictions





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- If the identified set is convex and the posterior of  $\phi$  is consistent, then the posterior mean bounds and the lower credible regions are consistent estimators of the true identified set
- Multiple prior ensure consistency, whereas estimated identified set using single prior is not consistent in the presence of partial identification

# Real data example

- Aruoba & Schorfheide (2011) SVAR

$$A_0 \begin{pmatrix} i_t \\ \Delta y_t \\ \pi_t \\ m_t \end{pmatrix} = c + A(L) \begin{pmatrix} i_t \\ \Delta y_t \\ \pi_t \\ m_t \end{pmatrix} + \begin{pmatrix} \epsilon_{it} \\ \epsilon_{yt} \\ \epsilon_{\pi t} \\ \epsilon_{mt} \end{pmatrix}$$

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- Compare to single prior approach (uniform prior)

# Results

- Consider different combinations of restrictions

**Table 1: Models and Posterior Plausibility**

Restrictions	I	II	III	IV	V	VI	VII
(i) $a_{12} = 0$	-	x	-	-	x	x	-
(ii) $IR^0(y, i) = 0$	-	-	x	-	x	-	x
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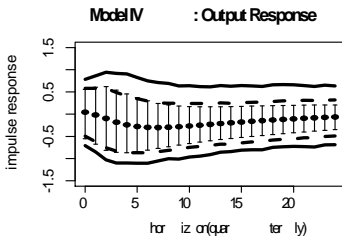
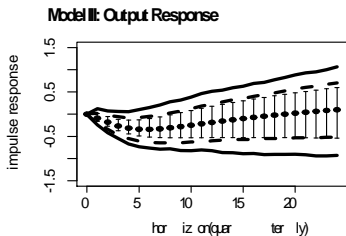
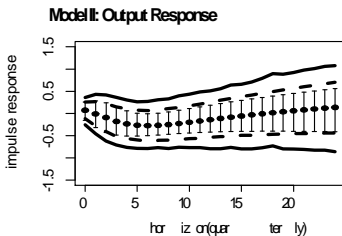
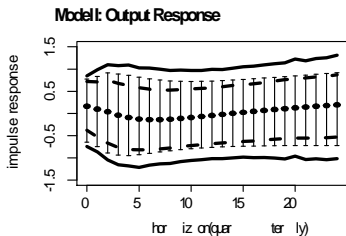
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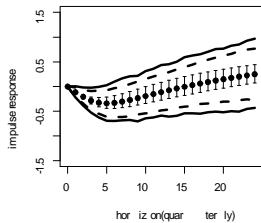
- Report output response to monetary policy shock

# Results - Models I-IV

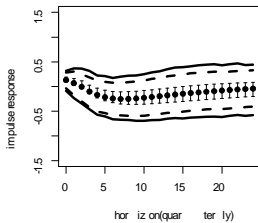


# Results - Models V-VII

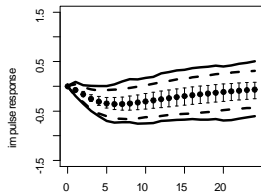
Model V : Output Response



Model VI: Output Response



Model VII: Output Response



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- Single prior and robust prior approaches can lead to different conclusions

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- Extension: joint credible regions (probably too wide to be useful....)